Statistische Methoden in der Computerlinguistik

1 Probability Theory

1.1 What is "Probability"?

1.1.1 Classical Definition

The probability P(A) of an event A is defined as the ratio of the number n(A) of occurrences of instances of that event to the number n of possible instances:

$$P(A) := \frac{n(A)}{n}$$

Problem(s):

- a posteriori: empirically motivated definition
- circular: simple events A must be equiprobable

1.1.2 Statistical Definition

Probability is defined in terms of relative frequency: the ratio h(A) of the number of event instances to the total number of events in a concrete experiment:

$$h(A) := \frac{n(A)}{n}$$
$$P(A) := \lim_{n \to \infty} h(A)$$

Problem(s):

- empirically motivated, yet not empircally groundable
- also works out to be circular

1.1.3 Axiomatic Definition (Kolmogoroff)

Basic Building Blocks:

- Ω : the sample space, a set of basic outcomes.
- $S \subseteq 2^{\Omega}$: the event space, a σ -field on Ω :

- non-empty: $S \neq \emptyset$
- closed under complement: $\forall x \in S : \overline{x} \in S$
- closed under union: $\forall x, y \in S : x \cup y \in S$

A probability distribution for an event space S is a (total) function: $P: S \to \mathbb{R}$ which fulfills Axioms (1) through (3):

- 1. For arbitrary events $A \in S : A \in S : P(A) \ge 0$
- 2. $P(\Omega) = 1$
- 3. For arbitrary sequences of pairwise disjoint events $A_1, A_2, \ldots \in S$:

$$P\left(\bigcup_{i=1}^{\infty} A_i\right) = \sum_{i=1}^{\infty} P(A_i)$$

Theorem 1 (Empty Event)
$$P(\emptyset) = 0$$

Theorem 2 (Finite Sums) For arbitrary finite sequences of pairwise disjoint events A_1, A_2, \ldots, A_n :

$$P\left(\bigcup_{i=1}^{n} A_i\right) = \sum_{i=1}^{n} P(A_i)$$

Theorem 3 (Subtraction Rule) For arbitrary $A \in S$:

$$P(A) = 1 - P(A)$$

Theorem 4 (Probability Range) For arbitrary $A \in S$:

$$0 \le P(A) \le 1$$

Theorem 5 (Subevent Probability) For $A, B \in S$:

$$A \subseteq B \Rightarrow P(A) \le P(B)$$

Theorem 6 (Addition Rule) For arbitrary $A, B \in S$:

$$P(A \cup B) = P(A) + P(B) - P(A \cap B)$$

Law of Large Numbers: Given the axioms (and theorems) above, we can approach the statistical definition of probability (see Section 1.1.2) from the other side: since the relative frequency $\frac{n(A)}{n}$ can vary between experimental runs, we can speak of the probability that it lies in a given interval. If the actual probability of the event is P(A), then we can say for an arbitrary $\varepsilon \in \mathbb{R}$ that:

$$\lim_{n \to \infty} P\left(\left| \frac{n(A)}{n} - P(A) \right| < \varepsilon \right) = 1$$

This assertion is known as the Law of Large Numbers.

1.2 Stochastic (in)Dependence

Definition 1 (Stochastic Independence) Two events A and B are said to be independent iff:

$$P(A \cap B) = P(A) \times P(B)$$

Theorem 7 If two events A and B are independent, then A and \overline{B} , \overline{A} and B, as well as \overline{A} and \overline{B} are also independent.

1.2.1 Conditional Probability

Definition 2 Given P(B) > 0, the conditional probability of A given B P(A|B) is defined as:

$$P(A|B) := \frac{P(A \cap B)}{P(B)}$$

Theorem 8 Assuming P(B) > 0, two events A and B are independent iff

$$P(A|B) = P(A)$$

Theorem 9 (Multiplication Rule) For all $A, B \in S$:

$$P(B)P(A|B) = P(A \cap B) = P(A)P(B|A)$$

Theorem 10 (Chain Rule) For $n \in \mathbb{N}$, $A_1, \ldots, A_n \in S$:

$$P(A_1 \cap \dots \cap A_n) = P(A_1)P(A_2|A_1)P(A_3|A_1 \cap A_2) \cdots P(A_n|A_1 \cap \dots \cap A_{n-1})$$

... somewhat prettier:

$$P\left(\bigcap_{i=1}^{n} A_{i}\right) = \prod_{i=1}^{n} P\left(A_{i} \left| \bigcap_{j=1}^{i-1} A_{j} \right.\right)$$

Theorem 11 (Bayes' Theorem)

$$P(B|A) = \frac{P(A|B)P(B)}{P(A)}$$